

DOE Project Controlled System Separation Study

Schedule and Status

DRAFT - FOR DISCUSSION PURPOSES ONLY

Schedule

- Enernex is working on a combination Task #2/Task #3 report due April 1
 - Task #2 is to develop criteria and control algorithms that are able to determine the need/trigger events for system separation and the interfaces where that should occur
 - Task #3 is to identify interfaces for system separation examining things such as coherent generation groups

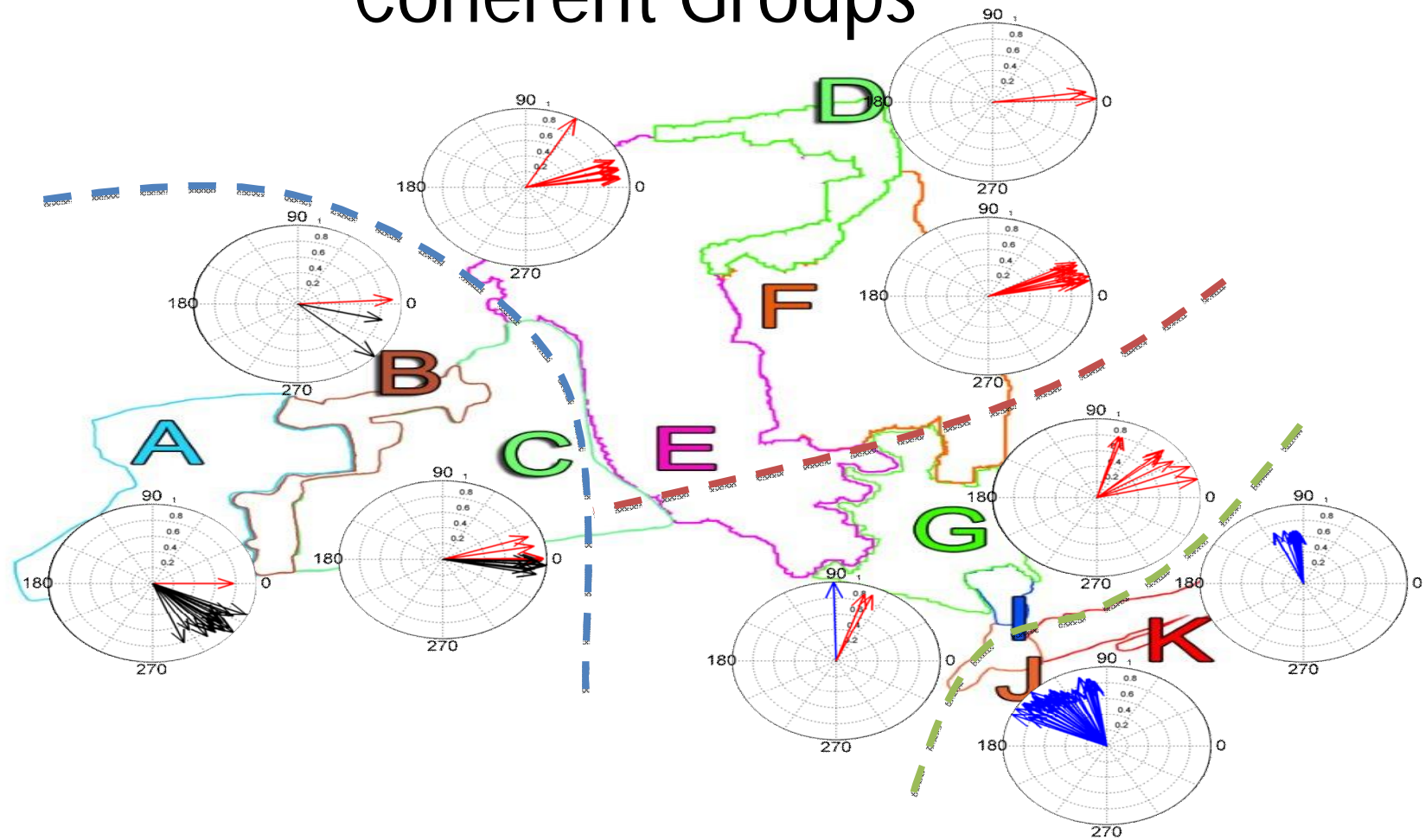
Schedule

- Next step after combination Task #2/Task #3 report is to complete a combination Task #4/Task #5 report due June 1
 - Task #4 is to determine appropriate locations for Dynamic Data Sources (PMU, DFR, etc.) to implement CSS
 - Task #5 is to identify the timing for when the CSS scheme would need to operate

Status

- Enernex issued a draft Task #2 report on January 27th
 - They examined an approach to use Transient Energy Function (TEF) to explain the mechanism of generator separation
 - Spectral Analysis-Based Method Validation was tested using the Power Spectrum Density (PSD) and Cross Spectrum Density (CSD) to determine generator coherency

Impact of Disturbance Type/Location to Coherent Groups



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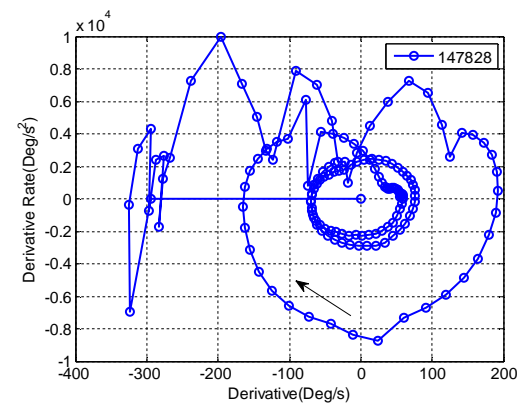
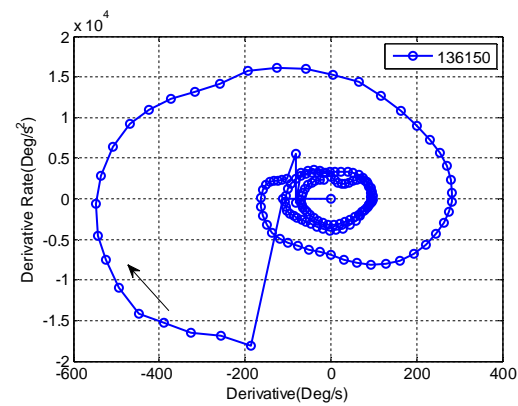
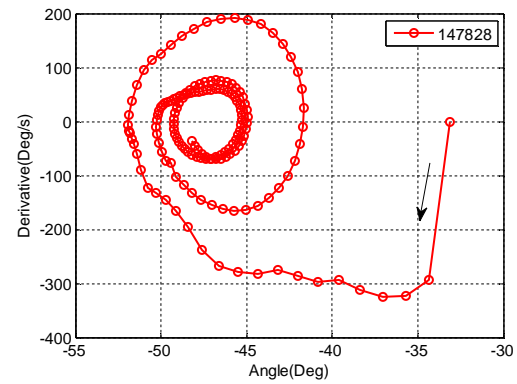
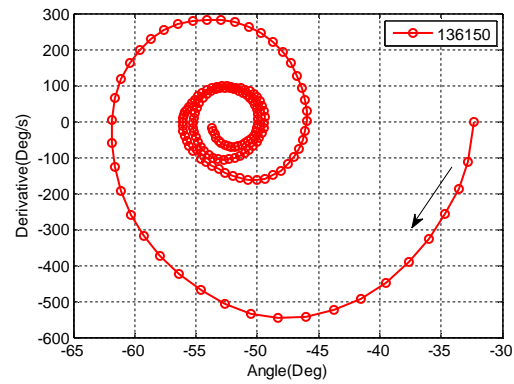
Enernex is now looking into Separation Indicators

- Look at angle, velocity of angle and acceleration of angle at a bus
- Look at angle, velocity of angle and acceleration of angle between buses

Trajectory Comparison

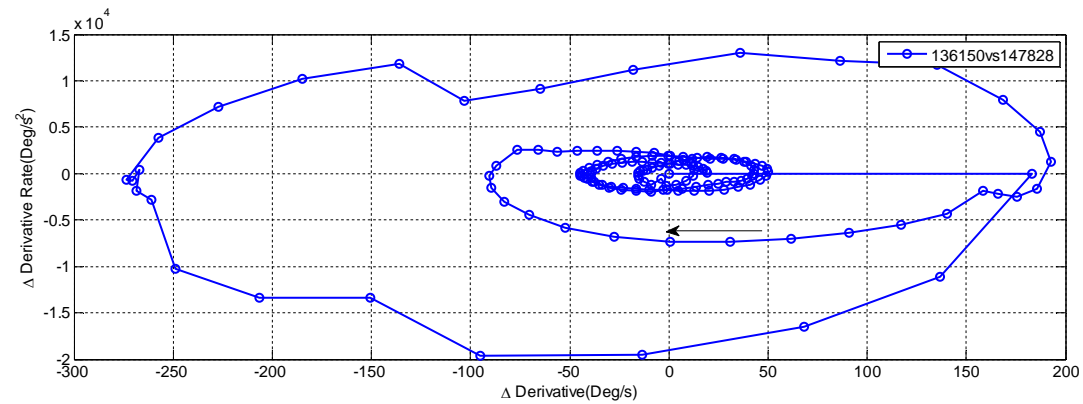
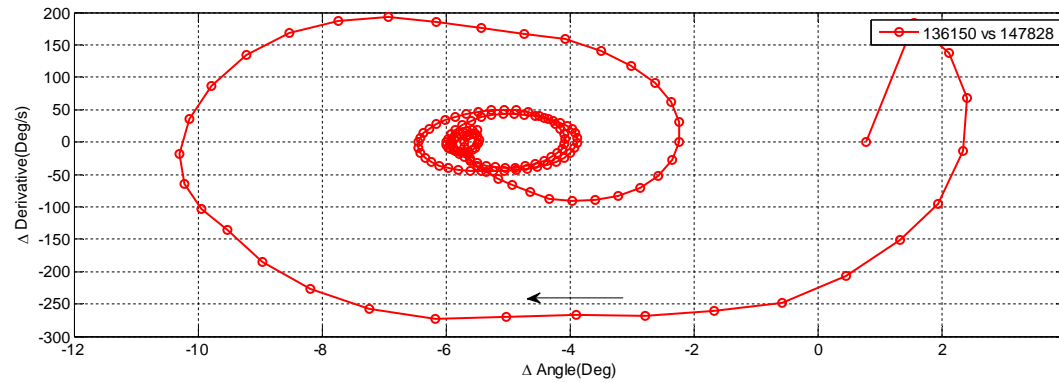
- Examine a trajectory comparison between these values
 - For example
 - Bus velocity versus Bus angle
 - Bus acceleration versus Bus velocity
 - Delta bus velocity versus delta bus angle
 - Delta bus acceleration versus delta bus angle

Bus Value Trajectory



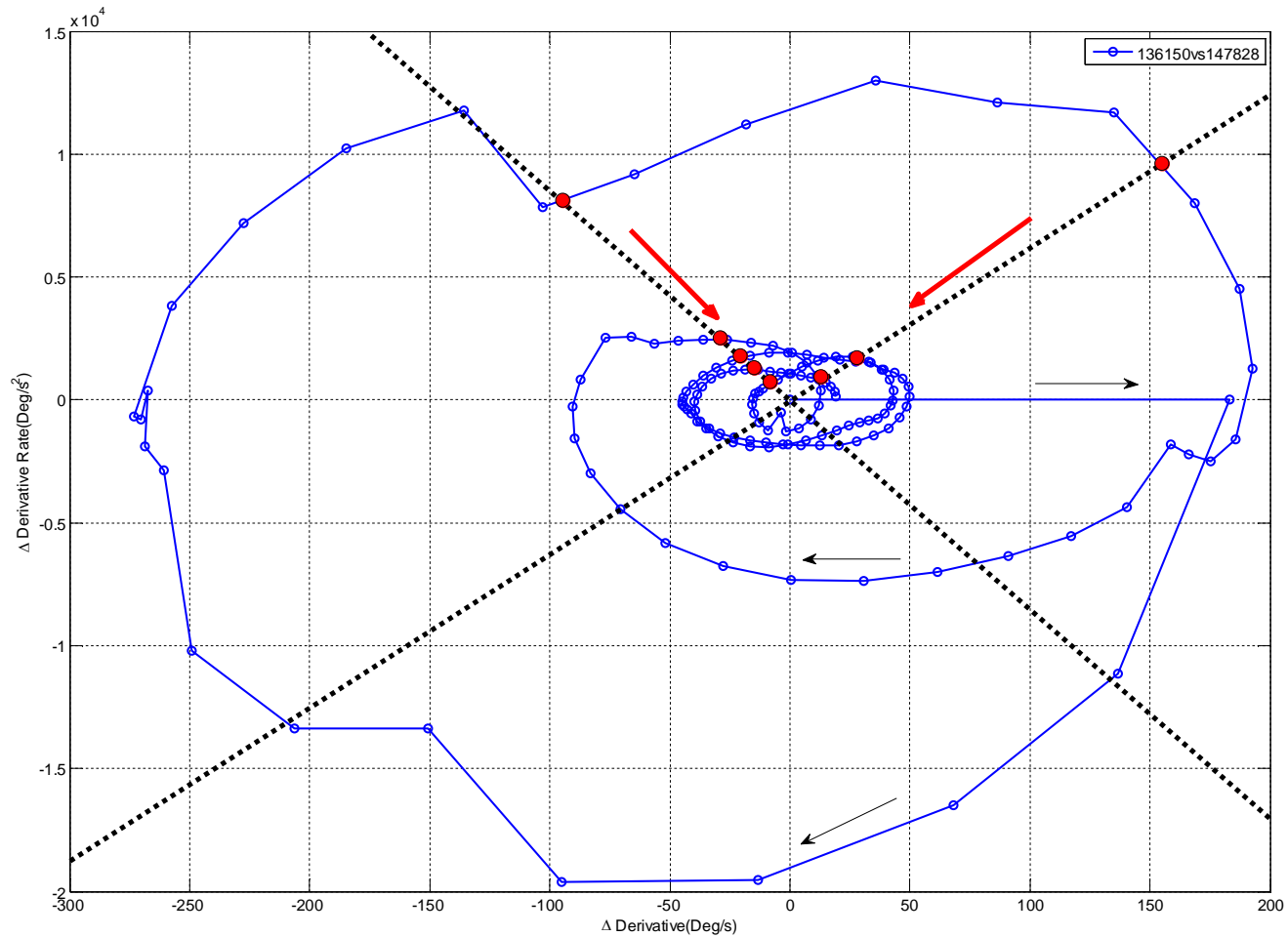
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Delta Bus Value Trajectory



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Convergent Attractor for Stable Case



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Observation

- For a stable case, the pre-fault equilibrium will reach a new equilibrium following a trajectory of eccentric periodic orbits. The moving direction of the trajectory is to minimize the distance between the point on the trajectory and the new equilibrium.
- An attractor can be observed in the trajectory.
- A correlation coefficient can be calculated between buses

Comprehensive Separation Indicators

- Assuming two monitoring locations and monitored signals are: $\delta_1, \omega_1, \alpha_1$ and $\delta_2, \omega_2, \alpha_2$
 - Step 1: α_1 and α_2 are constant -> normal
 - Step 2: Either α_1 or α_2 increases, or $\Delta \alpha_{12}$ increases -> warning 1
 - Step 3: Either ω_1 or ω_2 increases, or $\Delta \omega_{12}$ increases -> warning 2
 - Step 4: $\Delta \delta_{12} > 40^\circ$ -> warning 3 and launch correlation analysis between δ_1 and δ_2 and trajectory analysis for $\Delta \omega_{12}$ vs. $\Delta \alpha_{12}$
 - Step 5: In a 0.5 second window, compute correlation coefficient and attractors in the trajectory
 - Step 6: Refer to the Look-up Table in the next slide

Look up table

Indicator	Event
Corrcoef > 0.5, convergent attractor	Coherent and stable
Corrcoef > 0.7, divergent attractor	Coherent but unstable
$0 < \text{Correcoef} < 0.7$, convergent attractor	Out-of-phase oscillation (0 - 90°) and stable
$0 < \text{Correcoef} < 0.7$, divergent attractor	Out-of-phase oscillation (0 - 90°) but unstable
Correcoef < 0, convergent attractor (?)	Transient OOS
Correcoef < 0, non-attractor	Separation